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# **Probabilistic Reasoning for Time Series**

To describe an ever changing world we can use a series of random variables describing the world state at any time instant!

$$X_1 \rightarrow X_2 \rightarrow X_3 \rightarrow X_4 \rightarrow \dots$$

- It represents a sequence of states:  $X_1, X_2, X_3, \ldots$
- The transition from  $X_{t-1}$  to  $X_t$  depends only on  $X_{t-1}$

 $P(X_t | X_{t-1}, X_{t-2}, ..., X_t, X_0) = P(X_t | X_{t-1})$  (Markov Property)

- When transition probabilities are the same a any t, we are facing a stationary process.
- A <u>Bayesian Network</u> that forms a chain!

### (Let's skip basic stuff and go to hidden models)

# **Stochastic Processes and Markov Chains**

- Given  $X_t$  the value of a system characteristic at time t described as a (state) random variable, we have:
  - <u>Discrete Stochastic Process</u>: describes the a relationship between the stochastic description of a system  $(X_0, X_1, X_2, ...)$  at some discrete time steps.
  - A <u>Continuous Stochastic Process</u> is a stochastic process where the state can be observed at any time.
- A Discrete Stochastic Process is a (first order) Markov Chain when we have thet box t = 1, 2, 3, ... and for all n states it holds:

• 
$$P(X_{t+1}=i_{t+1}|X_t=i_t, X_{t-1}=i_{t-1},...,X_1=i_1,X_0=i_0)=P(X_{t+1}=i_{t+1}|X_t=i_t)$$

• Whenever the probability of an event is independent from time the Markov Chain is <u>Stationary</u>:  $P(X_{t+1}=j|X_t=i)=p_{ij}$ 

### **Markov Chain Description**

 A Markov Chain can be described using a Transition Matrix where p<sub>ij</sub> describes the probability of getting into state j starting from state i:

$$P = \begin{pmatrix} p_{11}p_{12}p_{13}\dots p_{1n} \\ p_{21}p_{22}p_{23}\dots p_{2n} \\ \dots \\ p_{n1}p_{n2}p_{n3}\dots p_{nn} \end{pmatrix} \qquad \sum_{j=1}^{n} p_{ij} = 1$$

• This transition matrix can be described also using a directed graph





# **Computing Probabilities**

 Given a Markov Chain in state i at time m we can compute states probability after n time steps:

$$P(X_{m+n}=j|X_m=i)=P(X_n=j|X_0=i)=P_{ij}(n)$$

If we take n=2 we have

 $P_{ij}(2) = \sum_{k} p_{ik} \cdot p_{kj}$  Scalar product of row *i* and column *j* 

• In general 
$$P_{ij}(n) = ij-th$$
 element of  $P^{n}$ .

 The probability of being in a given state j at time n without knowing the exact state of Markov Chain at time 0 is thus:

$$\sum_{i} q_{i} \cdot P_{ij}(n) = q \cdot (\text{column } j \text{ of } P^{n})$$

where:

# The Cola Example (I)

 Suppose our company produces two brands of Cola (i.e., Cola I, and Cola2) and there are no other Colas on the market. A person buying Cola I will buy Cola I again with probability 0.9. A persona buying Cola2 will buy Cola2 again with probability 0.8.

$$P = \begin{array}{c} \text{Cola1} & \text{Cola2} \\ \text{Cola1} & \begin{array}{c} 0.90 & 0.10 \\ 0.20 & 0.80 \end{array} \end{array} \right)$$

- Someone has bought Cola2, what's the probability he/she will buy Cola1 after 2 times?
- Someone has bought Colal, what's the probability he/she will buy Colal again after 3 times?
- Suppose at some time 60% of clients bought Colal and 40% Cola2. After three purchases what's the percentage of people buying Colal?

# The Cola Example (II)

Someone has bought Cola2, what's the probability he/she will buy Cola1 after 2 times?

• 
$$P(X_2 = I | X_0 = 2) = P_{2I}(2)$$
  
 $P2 = \begin{pmatrix} 0.90 & 0.10 \\ 0.20 & 0.80 \end{pmatrix} \begin{pmatrix} 0.90 & 0.10 \\ 0.20 & 0.80 \end{pmatrix} = \begin{pmatrix} 0.83 & 0.17 \\ 0.66 \end{pmatrix}$ 

Someone has bought Cola I, what's the probability he/she will buy Cola I again after 3 times?

$$P(X_3 = I | X_0 = I) = P_{II}(3)$$

$$P(3 = \begin{bmatrix} 0.83 & 0.17 \\ 0.34 & 0.66 \end{bmatrix} \begin{bmatrix} 0.90 & 0.10 \\ 0.20 & 0.80 \end{bmatrix} = \begin{bmatrix} 0.219 \\ 0.438 & 0.562 \end{bmatrix}$$

# The Cola Example (III)

Suppose at some time 60% of clients bought Cola1 and 40% Cola2. After three purchases what's the percentage of people buying Cola1?

$$p = \sum_{i} q_{i} \cdot P_{ij}(3) = q \cdot (\text{column } I \text{ of } P^{3})$$

$$p = \left(\begin{array}{cc} 0.60 & 0.40 \end{array}\right) \left(\begin{array}{c} 0.781 \\ 0.438 \end{array}\right) = 0.6438$$

Note: What we have discussed so far is the first-order Markov Chain.
 More generally, in k<sup>th</sup>-order Markov Chain, each state transition depends on previous k states.



### What's the size of transition probability matrix?



# **A Bunch of Definitions**

- Given a Markov Chain we define:
  - State *j* is <u>reachable</u> from *i* if it exist a path from *i* to *j*
  - States i and j <u>communicate</u> if i is reachable from j and viceversa
  - A set of states S in a Markov Chain is <u>closed</u> if no state outside S is reachable from a state in S
  - A state *i* is an <u>absorbing</u> state if  $p_{ii} = I$
  - A state *i* is <u>transient</u> if exists *j* reachable from *i*, but *i* is not reachable from *j*
  - A state that is not transient is defined as <u>recurrent</u>
  - A state *i* is <u>periodic</u> with period k>1 if k is the biggest number that divides the length of all path from *i* to *i*
  - A state that is not periodic is said <u>a-periodic</u>
- If all states in a Markov Chain are recurrent, a-periodic, and communicate with each other, it is said to be <u>Ergothic</u>



Examples of Ergothic Markov Chains

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### **Steady State Distribution**

 Being P the transition matrix of an Ergothic Markov Chain with n states we have that

 $\lim_{n\to+\infty} \boldsymbol{P}_{ij}(n) = \pi_j$ 

• With  $\pi = [\pi_1 \ \pi_2 \ \pi_3 \ \dots \ \pi_n] = \pi \cdot P$  being the <u>Steady State Distribution</u>



## **Transitory Behavior**

The behavior of a Markov Chain before getting to the Steady State id defined <u>transitory</u>

 We can compute the expected number of transition to reach state j being in state i for an Ergothic Markov Chain:

$$m_{ij} = p_{ij}(I) + \sum_{k \neq j} p_{ik} \cdot (I + m_{kj}) = I + \sum_{k \neq j} p_{ik} \cdot m_{kj}$$

- The Cola Example:
  - How many bottle on average a Cola I buyer will have before switching to Cola2?

 $m_{21} = 5$ 

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$$m_{12} = I + \sum_{k \neq j} p_{1k} \cdot m_{k2} = I + 0.9 \ m_{12} \qquad m_{12} = I C$$

What about viceversa?

$$m_{2l} = l + \sum_{k \neq j} p_{2k} \cdot m_{kl} = l + 0.8 \ m_{2l}$$



# **Dealing with Absorbing States**

- We have and <u>absorbing Markov Chain</u> if there exist one or more absorbing states and all the other are transient.
- For an absorbing Markov Chain we can write the transition matrix as:

$$\mathsf{P} = \left(\begin{array}{c|c} Q & R \\ \hline 0 & I \end{array}\right)$$

• where:

- Q is the transition matrix for transient states
- *R* is the trantion matrix from transient to absorbing states
- What kind of inference we could make with this model?
  - How long it will take to get in an absorbing state given that we start from a transient one?
  - Starting from a transient state, how long does it takes to get to an absorbing one?



# **Inference in Absorbing Markov Chains**

- How long I remain in a transient state given that we start from a transient one?
  - Being in a transient state *i* the average time spent in a transient state *j* is the *ij*-th element of (*I-Q*)<sup>-1</sup>
- Starting from a transient state, how long does it takes to get to an absorbing one?
  - Being in transient state *i* the probability to get into an absorbing state *j* is the *ij*-th element of  $(I-Q)^{-1} \cdot R$
- <u>Example</u>: in a company there are 3 levels: junior, senior, partner. You can leave the company as partner or not
  - How long does a junior remains in the company?
  - What's the probability for a junior to leave the company as partner?

	J	S	Р	LN	LP 🔪	
P =	0.80	0.15	0	0.05	0	
	0	0.70	0.20	0.10	0	
	0	0	0.95	0	0.05	
	0	0	0	1	0	
	0	0	0	0	1	

# The Company Example

• How long does a junior remains in the company?

$$(I-Q)^{-1} = \begin{pmatrix} 5 & 2.5 & 10 \\ 0 & 3.3 & 13.3 \\ 0 & 0 & 20 \end{pmatrix}$$

- He/she will stay as Junior: m<sub>11</sub> = 5
- He/she will stay as Senior: m<sub>12</sub> = 2.5

17.5 years!

- He/She will stay as Partner:  $m_{13} = 10$
- What's the probability for a junior to leave the company as partner?

$$(I-Q)^{-1} \cdot R = \begin{pmatrix} 0.5 & 0.5 \\ 0.3 & 0.7 \\ 0 & 1 \end{pmatrix}$$

• He/She will end up in state LP:  $m_{12} = 0.5$ 

### **Exercise: Gambler's Ruin**

• Suppose we are a gambler and we start from a 3\$ capital, with probability p=1/3 we can win 1\$ and with probability 1-p=2/3 we loose 1\$. We fail if out capital get to 0 and we win if our capital becomes 5.

$$X_0=3$$
  $X_1=?$   $X_2=?$   $X_3=?$  ...

- We can describe our capital as a Markov Chain being  $X_t$  our capital:
  - Possible states: 0, 1, 2, 3, 4, 5
  - Transition probability:  $p(X_{t+1} = X_t + I) = I/3$ ,  $p(X_{t+1} = X_t I) = 2/3$
- What kind of reasoning can we apply to this model?
  - What's the probability of sequence 3, 4, 3, 2, 3, 2, 1, 0?
  - What's the probability of success for the gambler?
  - What's the average number of bets the gambler will make?

# Why Should I Care All This Crazy Math?

"Nice, but unless I want to gamble why should I care? I'm a computer engineer what this has to do with practical intelligent systems?"

 What do you this is the greatest revolution (or revolutionary company) on the web in the last decade?



- Assume a link from page A to page B is a recommendation of page B by the author of A (we say B is successor of A).
  - Quality of a page is related to its *in-degree*.
  - The of a page is related to the quality of pages linking to it
- This recursively defines the *PageRank* of a page [Brin & Page '98]

For a (better) detailed description feel free to read: <u>http://www-db.stanford.edu/~backrub/google.html</u> <u>http://www.iprcom.com/papers/pagerank/</u>

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### Google's PageRank

- Suppose the web is an Ergothic Markov Chain (I know this is a big assumption). Consider browsing as an infinite random walk (surfing):
  - Initially the surfer is at a random page
  - At each step, the surfer proceeds
    - to a randomly chosen web page with probability d
    - to a randomly chosen successor of the current page with probability I-d
- The <u>PageRank</u> of a page is the fraction of steps the surfer spends on it in the limit.





### **Definition of PageRank**

PageRank = the steady state probability for this Markov Chain

PageRank(u) = 
$$d + (1-d) \sum_{(v,u) \in E} PageRank(v) / outdegree(v)$$
  
• *n* is the total number of nodes in the graph  
• *d* is the probability of a random jump

PageRank(C) = d/n+(1-d)(1/4 PageRan(A) + 1/3 PageRank(B))

- Summarizes the "web opinion" about the page importance
  - Query-independent
  - It can be faked ... read the provided links if you are curious!







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# Hidden Markov Models (HMM)

 We may not observe directly the states. The we get another Bayesian Network named as <u>Hidden Markov Model</u> (HMM).



- An HMM is described by a quintuple <S,E,P,A,B>
  - $S : \{s_1, \dots, s_N\}$  are the values for the hidden states
  - $E : \{e_1, \dots, e_T\}$  are the values for the observations
  - *P*: probability distribution of the initial state
  - A: transition probability matrix
  - B: emission probability matrix

For a deeper description feel free to read: http://www.cs.ubc.ca/~murphyk/Bayes/rabiner.pdf



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# An Example: The Audio Spectrum

Audio Spectrum of the song for the Prothonotary Warbler



Audio Spectrum of the song for the Chestnut-sided Warbler



- What can we ask to an HMM?
  - What bird is this?
  - How will the song continue?
  - Is this bird sick?
  - What phases does this song have?  $\rightarrow$  Time Series Segmentation

- Time Series Classification
- **Time Series Prediction**
- **Outlier** Detection

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### **Another Time Series Problem**



- What can we ask to this HMM?
  - Will the stock go up or down?
  - What type stock is this (eg, risky)?
  - Is the behavior abnormal (eg, BF)?



- **Time Series Prediction**
- Time Series Classification
- → Outlier Detection

### **Music Analysis**



- What can we ask to this HMM?
  - Can we compose more of that? -> Time Series Prediction
  - Is this Beethoven or Bach?
  - Can we segment it into themes? -> Time Series Segmentation
- $\rightarrow$  Time Series Classification

### Weather: A Markov Chain Model





• What is the probability of this series?

$$P(s) = P(S_{sunny})P(S_{rainy}|S_{sunny})P(S_{rainy}|S_{rainy})P(S_{rainy}|S_{rainy})P(S_{snowy}|S_{rainy})$$
  
$$P(S_{snowy}|S_{snowy}) = 0.7 \cdot 0.15 \cdot 0.6 \cdot 0.6 \cdot 0.02 \cdot 0.2 = 0.0001512$$

### Weather: An Hidden Markov Models



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# **Ingredients and Fundamental Questions**

• Observations: { $O_{shorts}$ ,  $O_{coat}$ ,  $O_{umbrella}$ }

State transition probabilities:

• Observation probabilities:

 $A = \begin{bmatrix} 0.80 & 0.15 & 0.05 \\ 0.38 & 0.60 & 0.02 \\ 0.75 & 0.05 & 0.20 \end{bmatrix}$  $B = \begin{bmatrix} 0.60 & 0.30 & 0.10 \\ 0.05 & 0.30 & 0.65 \\ 0.00 & 0.50 & 0.50 \end{bmatrix}$ 

• Initial state distribution:

 $P = (0.7 \ 0.25 \ 0.05)$ 

- What is the probability of this series?
- What is the underlying sequence of state?
- How can I learn my HMM parameters?

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Given:

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# **Computing Forward Probability**

We define the Forward Probability as the probability of actual state and observations

$$P(X_t = s_i, e_{1:t})$$

- Why compute forward probability?
  - Probability of observations: P(e<sub>1:t</sub>).
  - Prediction: P(X<sub>t+1</sub>=s<sub>i</sub> | e<sub>1:t</sub>)=?

$$P(X_{t}=s_{i}, e_{1:t}) = P(X_{t}=s_{i}, e_{1:t-1}, e_{t})$$

$$= \sum_{j} P(X_{t-1}=s_{j}, X_{t}=s_{i}, e_{1:t-1}, e_{t})$$

$$= \sum_{j} P(e_{t}|X_{t}=s_{i}, X_{t-1}=s_{j}, e_{1:t-1})P(X_{t}=s_{i}, X_{t-1}=s_{j}, e_{1:t-1})$$

$$= \sum_{j} P(e_{t}|X_{t}=s_{i})P(X_{t}=s_{i}|X_{t-1}=s_{i}, e_{1:t-1})P(X_{t-1}=s_{j}, e_{1:t-1})$$

$$= \sum_{j} P(e_{t}|X_{t}=s_{j})P(X_{t}=s_{i}|X_{t-1}=s_{j}, e_{1:t-1})$$

$$\alpha_{i}(t) = P(X_{t} = s_{i}, e_{1:t})$$
  
=  $\sum_{j} P(X_{t} = s_{i} | X_{t-1} = s_{j}) P(e_{t} | X_{t} = s_{i}) \alpha_{j}(t-1)$   
=  $\sum_{j} A_{ij} B_{iet} \alpha_{j}(t-1)$ 

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Same form.

# The Viterbi Algorithm

• From observations, compute the most likely hidden state sequence:  $argmax P(x_{1:t}|e_{1:t}) = argmax P(x_{1:t}, e_{1:t})/P(e_{1:t})$ 

 $= \operatorname{argmax} P(x_{1:t}, e_{1:t})$ 

By applying the Bayesian Network factorization

 $P(x_{1:t}, e_{1:t}) = P(X_0) \prod_{i=1,t} P(X_i | X_{i-1}) P(e_i | X_i)$ 

• The solution we are looking for is the one that minimizes

 $-logP(X_{1:t}, e_{1:t}) = -logP(X_0) + \sum_{i=1,t} (-logP(X_i|X_{i-1}) - logP(e_i|X_i))$ 

- Given a HMM construct a graph that consists I+t\*N nodes:
  - One initial node and N node at time *i* where  $j^{th}$  represents  $X_i = s_i$ .
  - The link between the nodes X<sub>i-1</sub>=s<sub>j</sub> and X<sub>i</sub>=s<sub>k</sub> is associated with the length -log(P(X<sub>i</sub>=s<sub>k</sub> | X<sub>i-1</sub>=s<sub>j</sub>)P(e<sub>i</sub> | X<sub>i</sub>=s<sub>k</sub>))
- The problem becomes that of finding the shortest path from  $X_0 = s_0$  to one of the nodes  $X_t = s_t$ .





## **Baum-Welch Algorithm**

- The previous two kinds of computation needs parameters  $\mu$ =(P, A, B). Where do the probabilities come from?
- Solution: Baum-Welch Algorithm (special case of EM)
  - Unsupervised learning from observations
  - Find  $\operatorname{argmax}_{\mu} P\mu(e_{1:t})$
- Given an observation sequence, find out which transition probability and emission probability table assigns the highest probability to the observations:
  - I. Start with an initial set of parameters  $\mu_0$  (possibly arbitrary)
  - 2. Compute pseudo counts: how many times the transition from  $X_{i-i} = s_i$  to  $X_i = s_k$  occurred?
  - 3. Use the pseudo counts to obtain a better set of parameters  $\mu_1$
  - 4. Iterate until  $P_{\mu I}(e_{I:t})$  is not bigger than  $P_{\mu}(e_{I:t})$

## **Pseudo Counts and Backward Probability**

- Given the observation sequence e<sub>1:T</sub>,
  - pseudo count of state  $s_i$  at time t is the probability  $P(X_t = s_i | e_{1:T})$

$$P(X_{t}=s_{i}|e_{1:T}) = P(X_{t}=s_{i}, e_{1:t}, e_{t+1:T})/P(e_{1:T})$$
  
=  $P(e_{t+1:T}|X_{t}=s_{i}, e_{1:t})P(X_{t}=s_{i}, e_{1:t})/P(e_{1:T})$   
=  $P(e_{t+1:T}|X_{t}=s_{i})P(X_{t}=s_{i}|e_{1:t})P(e_{1:t})/P(e_{1:T})$   
=  $\alpha_{i}(t) \beta_{i}(t)/P(e_{t+1:T}|e_{1:t})$ 

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- pseudo counts of the link from  $X_t = s_i$  to  $X_{t+1} = s_j$  is the probability  $P(X_t = s_i, X_{t+1} = s_j | e_{1:T}) = P(X_t = s_i, X_{t+1} = s_j, e_{1:t}, e_{t+1}, e_{t+2:T}) / P(e_{1:T})$   $= P(X_t = s_i, e_{1:t}) P(X_{t+1} = s_j) / P(e_{t+1} | X_{t+1} = s_j) / P(e_{t+2:T} | X_{t+1} = s_j) / P(e_{1:T})$   $= P(X_t = s_i, e_{1:t}) A_{ij} B_{jet+1} P(e_{t+2:T} | X_{t+1} = s_j) / P(e_{1:T})$  $= \alpha_i(t) A_{ij} B_{jet} \beta_j(t+1) / P(e_{1:T})$
- Being  $\beta_j(t) = P(e_{t+1}, \dots, e_T | X_t = s_j)$  we can compute it backward
  - $\beta_j(T) = I;$

• 
$$\beta_j(t) = \Sigma_j A_{ij} B_{jet} \beta_j(t+1).$$

# **HMM Parameters Update**

 We can efficiently compute forward and backward probability for all the states in the Hidden Markov Model



To update our estimate of HMM parameters

- *count(i)*: the total pseudo count of state s<sub>i</sub>.
- count(i,j): the total pseudo count of transition from s<sub>i</sub> to s<sub>i</sub>.
- Add  $P(X_t = s_i, X_{t+1} = s_j | e_{1:T})$  to count(i, j)
- Add  $P(X_t = s_i | e_{1:T})$  to count(i)
- Add  $P(X_t = s_i | e_{1:T})$  to count(i,et)
- Updated A<sub>ij</sub> = count(i,j)/count(i)
- Updated B<sub>jet</sub>=count(j,e<sub>t</sub>)/count(j)



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# Summary on HMM

- HMMs are generative probabilistic models for time series with hidden information (state).
- There a few issues remaining:
  - Zero probability problem
    - Training sequence: AAABBBAAA
    - Test sequence: AAABBBCAAA
  - Finding "right" number of states, right structure
  - Numerical instabilities
- Beside these problems they are extremely practical, best known methods in speech recognition, computer vision, robotics, ...

You'd be surprised by the relationships between HMM and Kalman Filtering or Kalman Smoothing!